

eclipse muto

an adaptive framework and a runtime platform for dynamically composable model-driven software stacks for ROS



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eclipse mut0

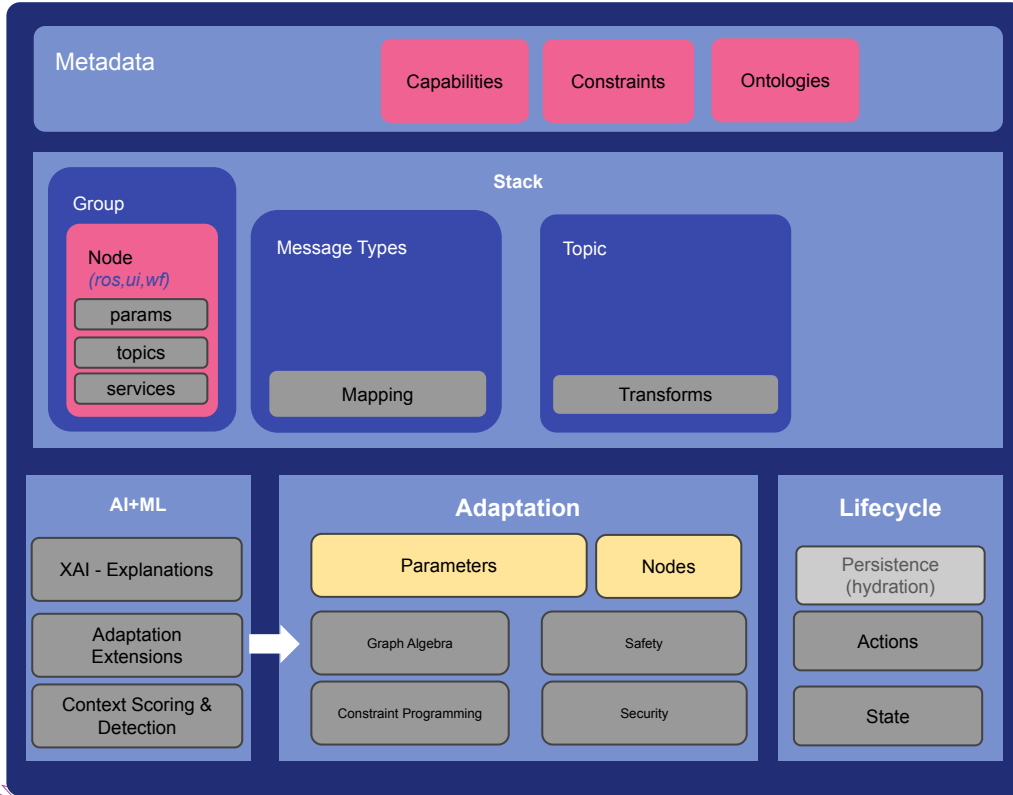
an adaptive framework and a runtime platform for dynamically composable model-driven software stacks for ROS



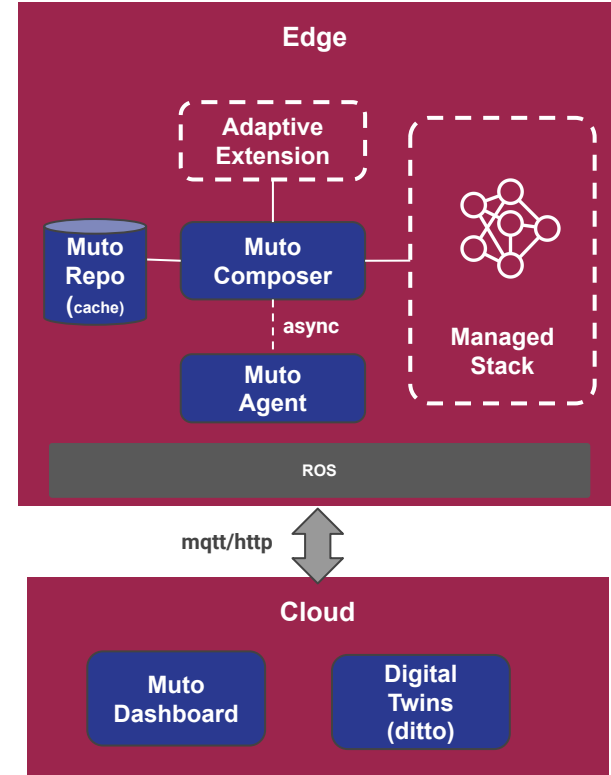
icons made by [bqlqn](https://www.flaticon.com/author/bqlqn) from [flaticon.com](https://www.flaticon.com)
Icons made by [freepik](https://www.flaticon.com/author/freepik) from [flaticon.com](https://www.flaticon.com)



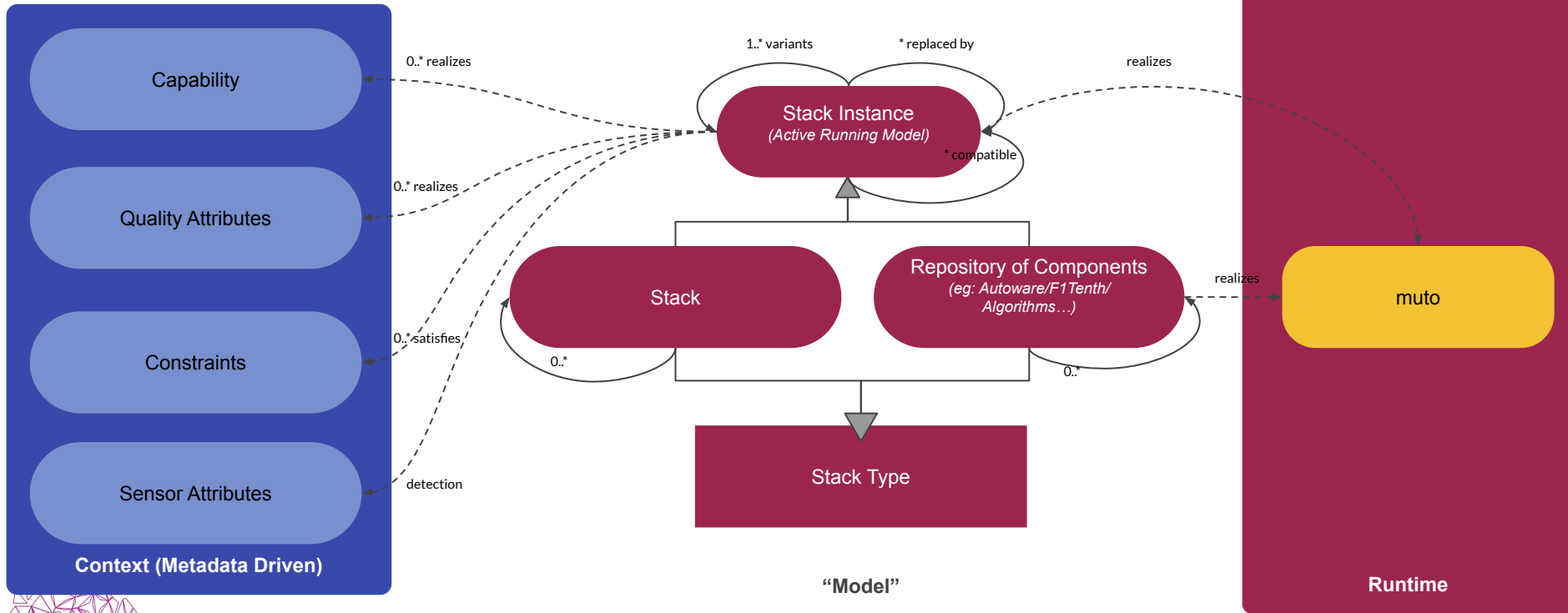
Overview



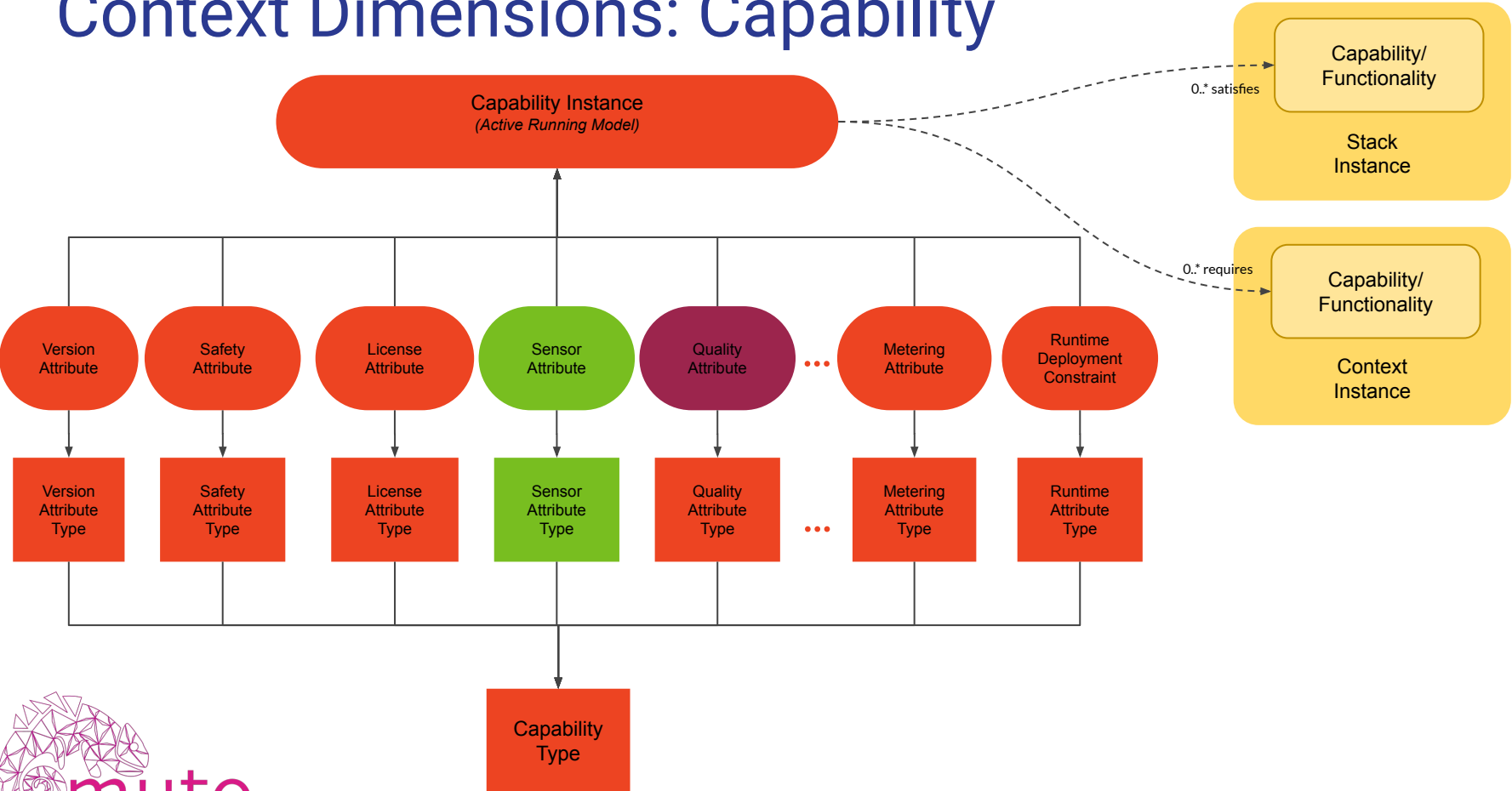
muto runtimes



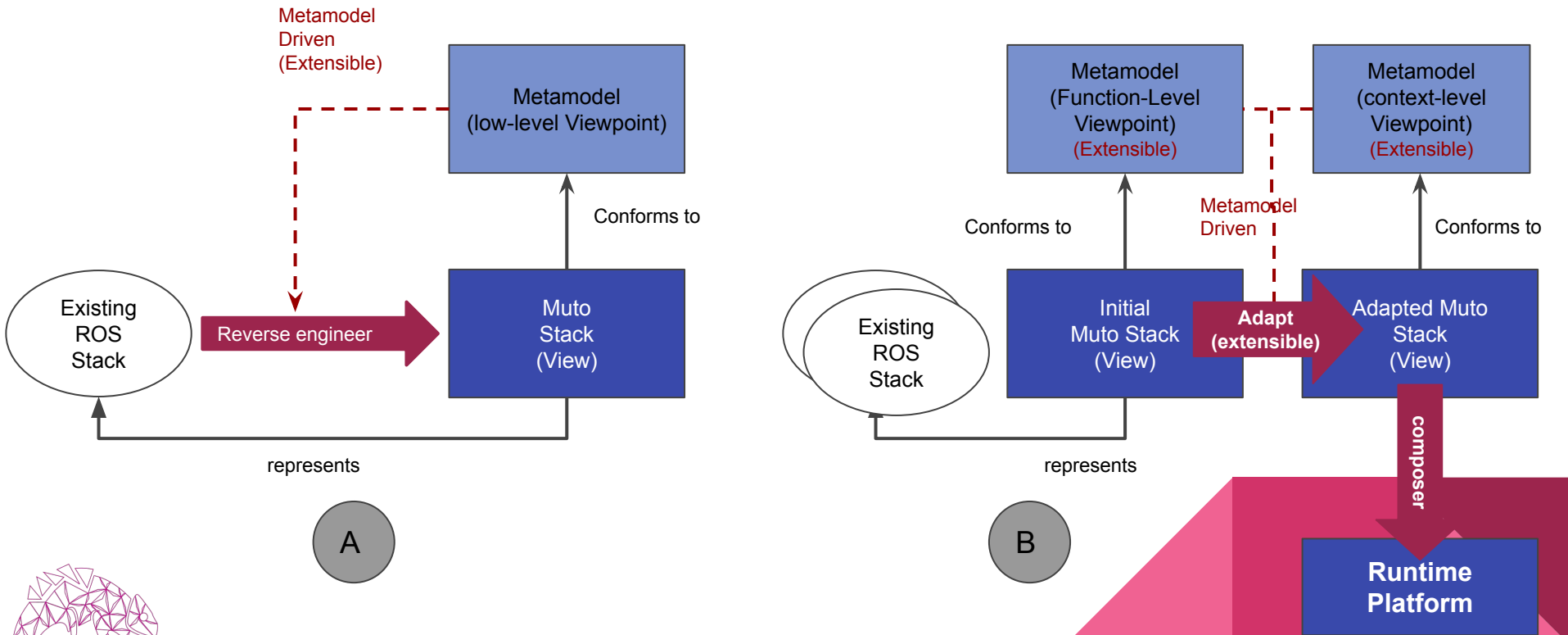
Contextual Adaptation



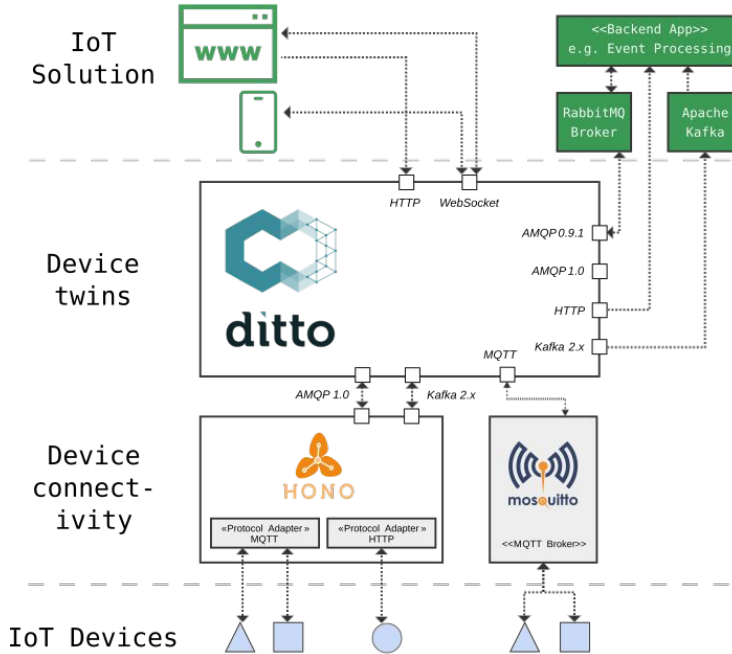
Context Dimensions: Capability



Adaptive Stacks (Model Driven)



muto uses ditto for stack and vehicle digital twins*

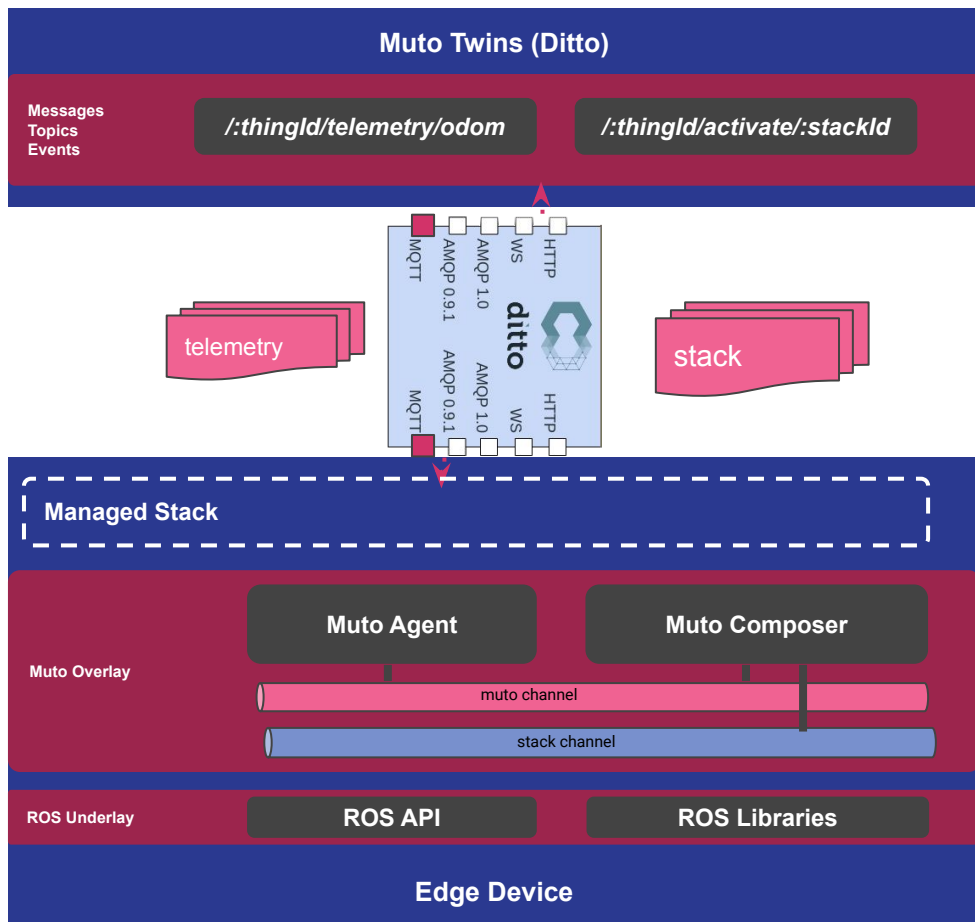


This diagram is reproduced from <https://www.eclipse.org/ditto>

**A digital twin is a virtual representation that serves as the real-time digital counterpart of a physical object or process.*

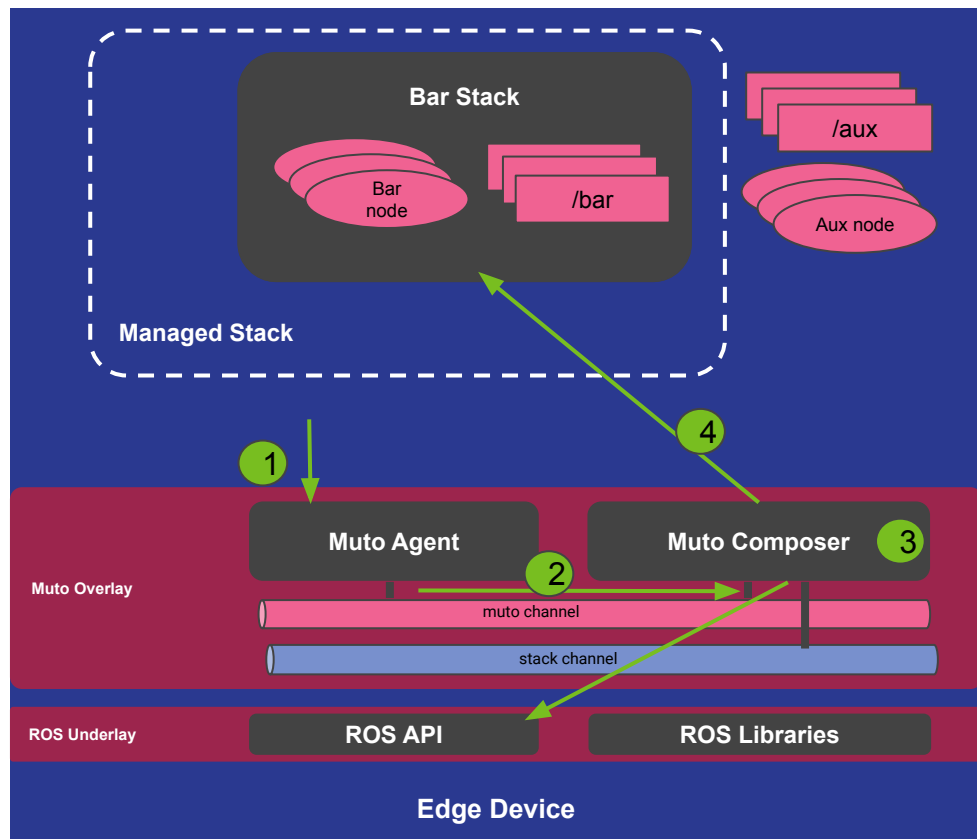
Muto Agent

- A runtime ROS component
- Acts as a gateway for remote management capabilities
 - i.e. eclipse ditto twins
- Bidirectional (cloud <-> edge)
 - Relays messages to *Composer* for stack lifecycle management
 - Streams edge device information
- Asynchronous



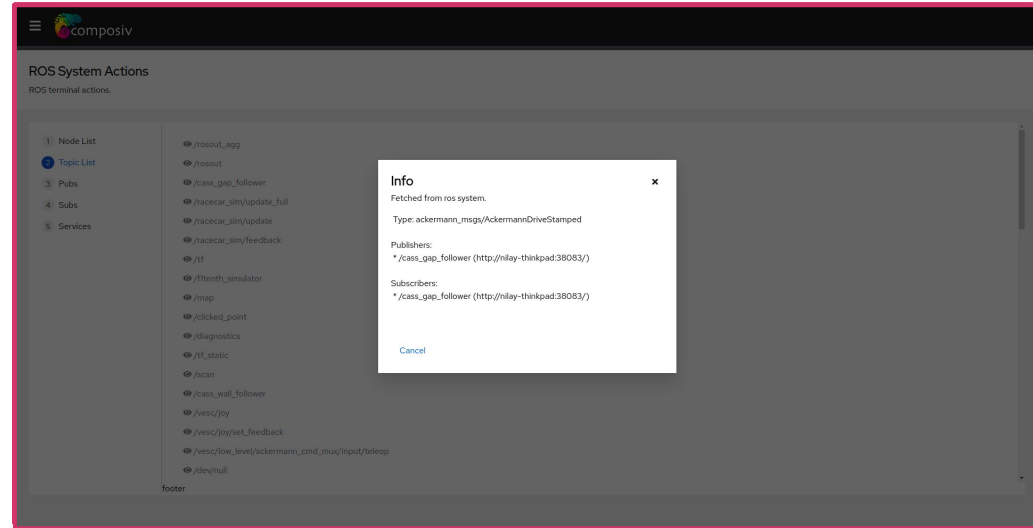
Muto Composer

- A runtime ROS component
- Composes and manages life cycle of ROS nodes defined by the stack model
- Node graph algebra
 - Stack introspection
 - Stack diff
 - Node Lifecycle actions
 - Interact with Param server



Muto Dashboard

- Centralized management
 - *'A dashboard to rule them all'*
- Extensible and modular
 - Composed of pluggable μ Frontends
 - (Muto LiveUI)
- Example modules
 - ROS Actions
 - Vehicles
 - Stack
 - Remote control
 - ROS Graph

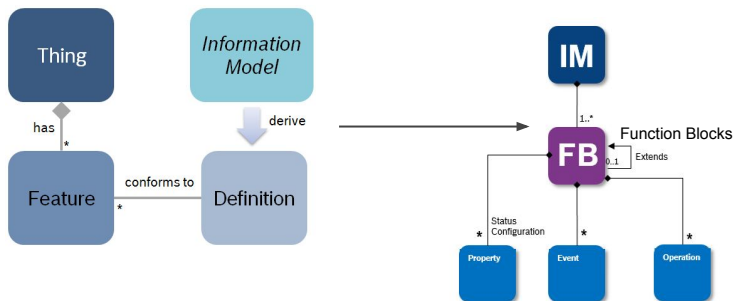


Vehicle

Associate a stack with a vehicle and manage its lifecycle

ROS State (nodes/topics/params)

Telemetry and sensor metadata



Class diagram for things from <https://www.eclipse.org/ditto>

```
{
  "thingId": "ai.composiv.sandbox.ftenth:donkeycar-nano-01",
  "policyId": "ai.composiv.sandbox.ftenth:donkeycar-nano-01",
  "definition": "ai.composiv.sandbox.ftenth.simulator:TestCar:1.0.0",
  "attributes": {
    "serial": "donkeycar-nano-01",
    "type": "simulator",
    "manufacturer": "Eteration"
  },
},
"features": {
  "context": {
    "properties": { ... }
  },
},
"stack": {
  "properties": {
    "current": {
      "stackId": "ai.composiv.sandbox.ftenth:donkey_base.launch",
      "state": "killed"
    }
  }
},
},
"telemetry": {
  "properties": { ... }
},
},
"sensors": {
  "properties": { ... }
},
},
"rosModel": { ... }
},
},
```



Stack

Stack Model

- Follows ROS constructs
 - args/params/nodes/topics/...
- Modular
 - reference other stack “things”

```
{
  "thingId": "ai.composiv.sandbox.fl1tenth:composiv_simulator_gf.launch",
  "policyId": "ai.composiv.sandbox.fl1tenth:composiv_simulator_gf.launch",
  "definition": "ai.composiv.sandbox.fl1tenth:Stack:1.0.0",
  "attributes": {
    "type": "simulator"
  },
  "features": {
    "stack": [
      {
        "properties": {
          "name": "Composiv Learning Simulator with Gap Follower",
          "context": "eteration_office",
          "stackId": "ai.composiv.sandbox.fl1tenth:composiv_simulator_gf.launch",
          "stack": [
            {
              "thingId": "ai.composiv.sandbox.fl1tenth:composiv_simulator.launch"
            }
          ],
          "node": [
            {
              "name": "cass_gap_follower",
              "pkg": "cass_gap_follower",
              "exec": "cass_gap_follower",
              "param": [
                {
                  "from": "${find cass_gap_follower}/params.yaml"
                }
              ]
            }
          ]
        }
      }
    ]
  }
},
```



More Complex Stack

```
{
  "thingId": "ai.composiv.sandbox.f1tenth:composiv_simulator.launch",
  "policyId": "ai.composiv.sandbox.f1tenth:composiv_simulator.launch",
  "definition": "ai.composiv.sandbox.f1tenth:Stack:1.0.0",
  "attributes": {
    "type": "simulator"
  },
  "features": {
    "stack": {
      "properties": {
        "name": "Composiv Learning Simulator (GF)",
        "context": "eteration_office",
        "stackId": "ai.composiv.sandbox.f1tenth:composiv_simulator.launch",
        "arg": [
          {
            "name": "map",
            "value": "${find f1tenth_simulator)/maps/levine_blocked.yaml"
          },
          {
            "name": "racecar_xacro",
            "value": "${find f1tenth_simulator)/racecar.xacro"
          }
        ],
        "param": [
          {
            "namespace": "racecar",
            "name": "robot_description",
            "command": "xacro $(arg racecar_xacro)"
          }
        ]
      },
    },
  },
}
```

```
node": [
  {
    "namespace": "racecar",
    "name": "robot_state_publisher",
    "pkg": "robot_state_publisher",
    "exec": "robot_state_publisher",
    "args": "${arg map}"
  },
  {
    "name": "map_server",
    "pkg": "map_server",
    "exec": "map_server",
    "args": "${arg map}"
  },
  {
    "name": "joy_node",
    "pkg": "joy",
    "exec": "joy_node"
  },
  {
    "name": "f1tenth_simulator",
    "pkg": "f1tenth_simulator",
    "exec": "simulator",
    "param": [
      {
        "from": "${find f1tenth_simulator)/params.yaml"
      }
    ],
    "output": "screen"
  },
  {
    "name": "mux_controller",
    "pkg": "f1tenth_simulator",
    "exec": "mux",
    "param": [
      {
        "from": "${find f1tenth_simulator)/params.yaml"
      }
    ],
    "output": "screen"
  },
  {
    "pkg": "f1tenth_simulator",
    "exec": "behavior_controller",
    "name": "behavior_controller",
    "param": [

```



muto f1tenth sandbox

f1tenth examples are used as a demonstration of eclipse muto

- Educational resource
- Support latest algorithms and hardware

F1

TENTH

<https://f1tenth.org/>



muto liveUI

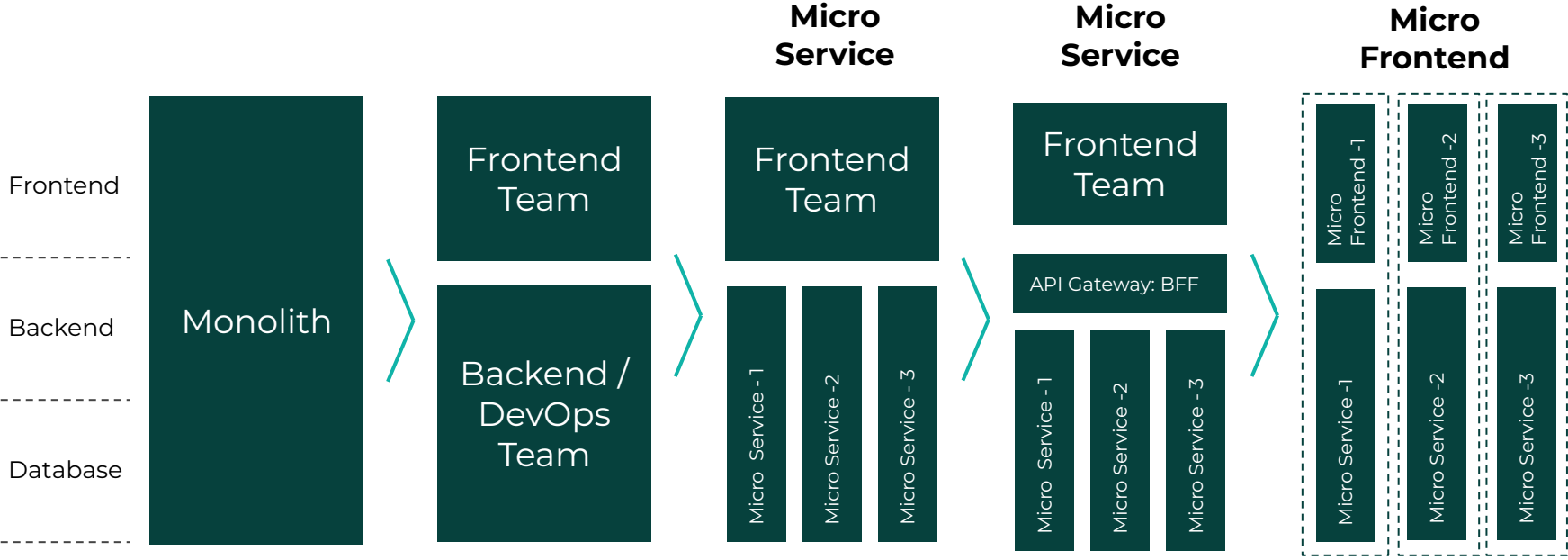
LiveUI helps you divide a monolithic frontend into smaller, more manageable micro frontends.

There is no magic, LiveUI allows you to split and manage your codebase, teams, release processes and runtimes independently



Composable at Runtime! LiveUI has the ability to change UI while its running

Micro Frontend ?



Independently Deployed

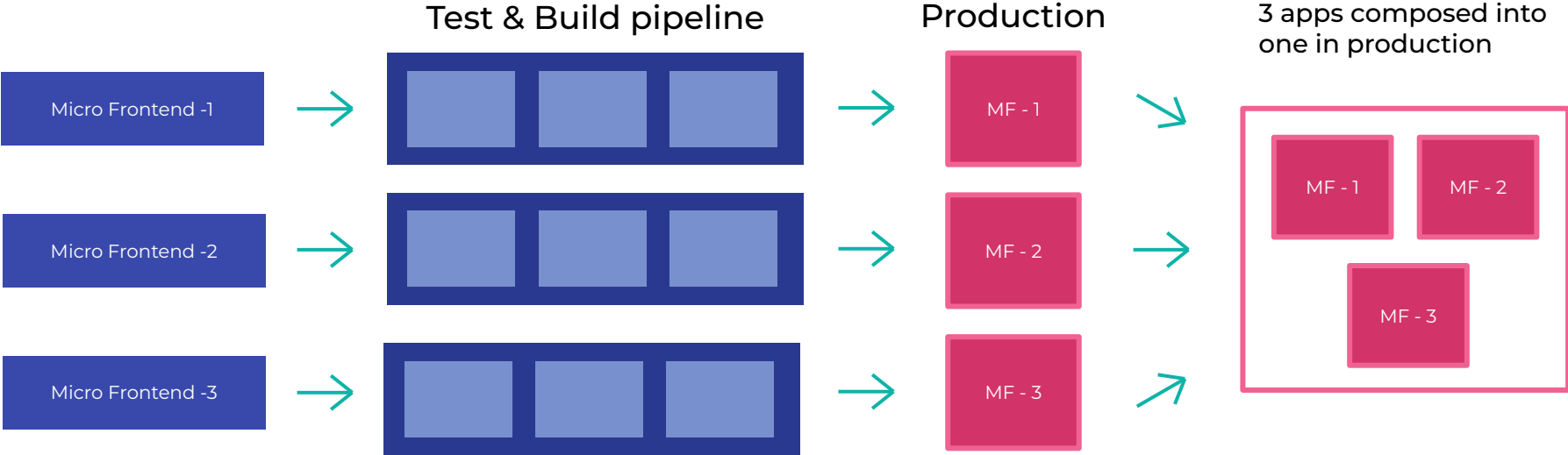


diagram reproduced from <https://martinfowler.com/articles/micro-frontends.html>



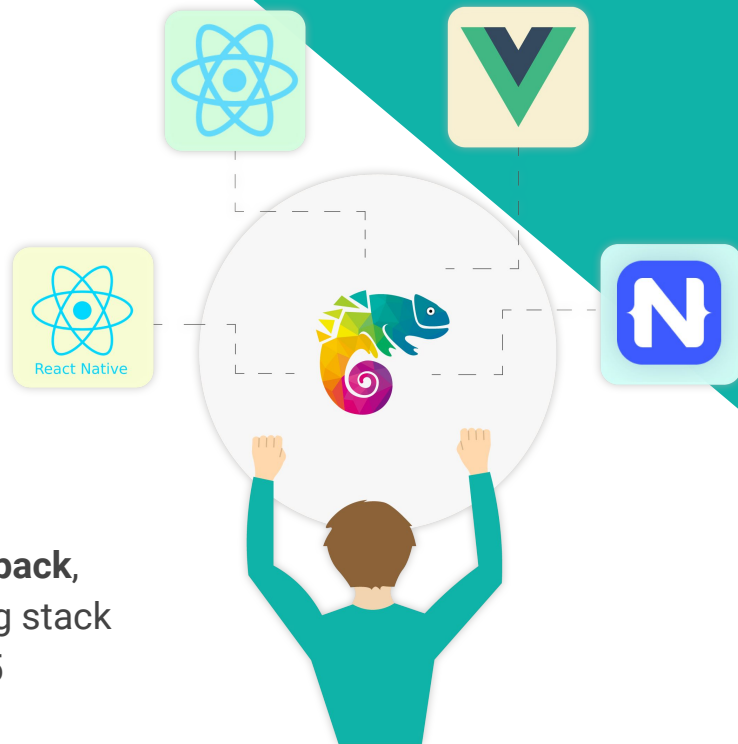
Framework Support

LiveUI is framework and bundler agnostic.

LiveUI works with

- **React.js**
- **React Native**
- **Vue.js**
- **NativeScript**

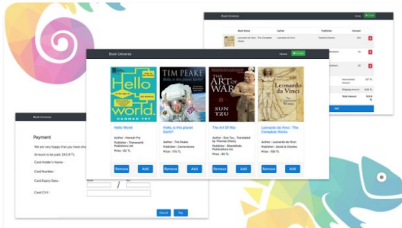
You can use with the bundler of your choice such as **Webpack**, **Metro** and others. It will reuse support from the underlying stack such as the upcoming Module federation from webpack 5 automatically, or default to its own.





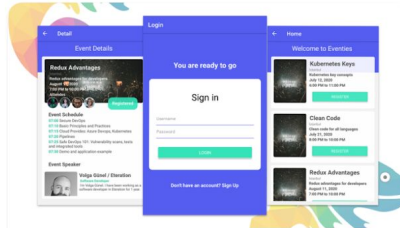
Showcase

Here is our sample projects that are built with LiveUI.



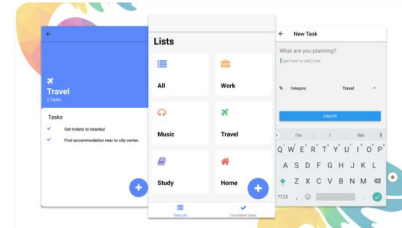
Book Universe (Multiple Code Bases of LiveUI for React)

E-commerce website with LiveUI. Live Payment Screen, live Categories and Cart components. This project is an example of multiple code bases for React.

[Document](#)[Source](#)

Eventies (Multiple Code Bases of LiveUI for React Native)

Event application with LiveUI. Live Login Screen, live Event Box and Event Details components. This project is an example of multiple code bases for React Native.

[Document](#)[Source](#)

ToDos (Single Code Base of LiveUI for React Native)

To Do application with LiveUI. Live To Do Boxes. This project is an example of single code base for React Native.

[Document](#)[Source](#)



Thank you !

- <https://projects.eclipse.org/proposals/eclipse-muto>
 - <https://liveui.composiv.ai>
 - **Soon:**
github.com/eclipse-muto



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