

Eclipse (Mo)bility (Ec)oSystem

Dirk Bangel, Indrasen Raghupatruni Systems Engineering BBM Technical Strategies and Enabling, Robert Bosch GmbH

Vision and Mission

Mission: "provides the most accessible and straight forward software development kit (SDK) for infrastructure-based solutions"

Wision: "to leverage interconnection and integration with all kind of in- and off-vehicle, as well as ecosystems, solution building blocks, enabling the software defined mobility"

We are sponsored by the **Sof** ar nce - paving the way for software defined vehicle.



Ecosystem ... Ecosystem ... Global traffic flow planner 旧日公 **Common Mobility Interface** \sim Local planner & control plane A L→ Co, Common Vehicle Interface Simulation vehicle controller Real vehicle controller ... vehicle controller 6 4 6



Application plane

for all the algorithmic tooling https://github.com/eclipse-moec/motioncontrol

- Specific agent behaviour
- Sensor and actuator data processing
- etc.

Data plane

for all integration purposes https://github.com/eclipse-moec/integration

- Signal mapping e.g., for CAN via DBC files
- Clock abstraction and timing e.g., for coordinating multiple actors
- etc.

Operating system (OS) as control plane, via <u>Eclipse LEDA</u>

- Board Support Package (BSP)
- Over the air update and configuration manager (UCM)
- Mandatory functional packages, at least communication middleware and message definitions

Maximum hardware abstraction and environment specific independence, fully loaded with application examples.

No specialized build system.





THANK YOU!

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