



eCAL ecosystem

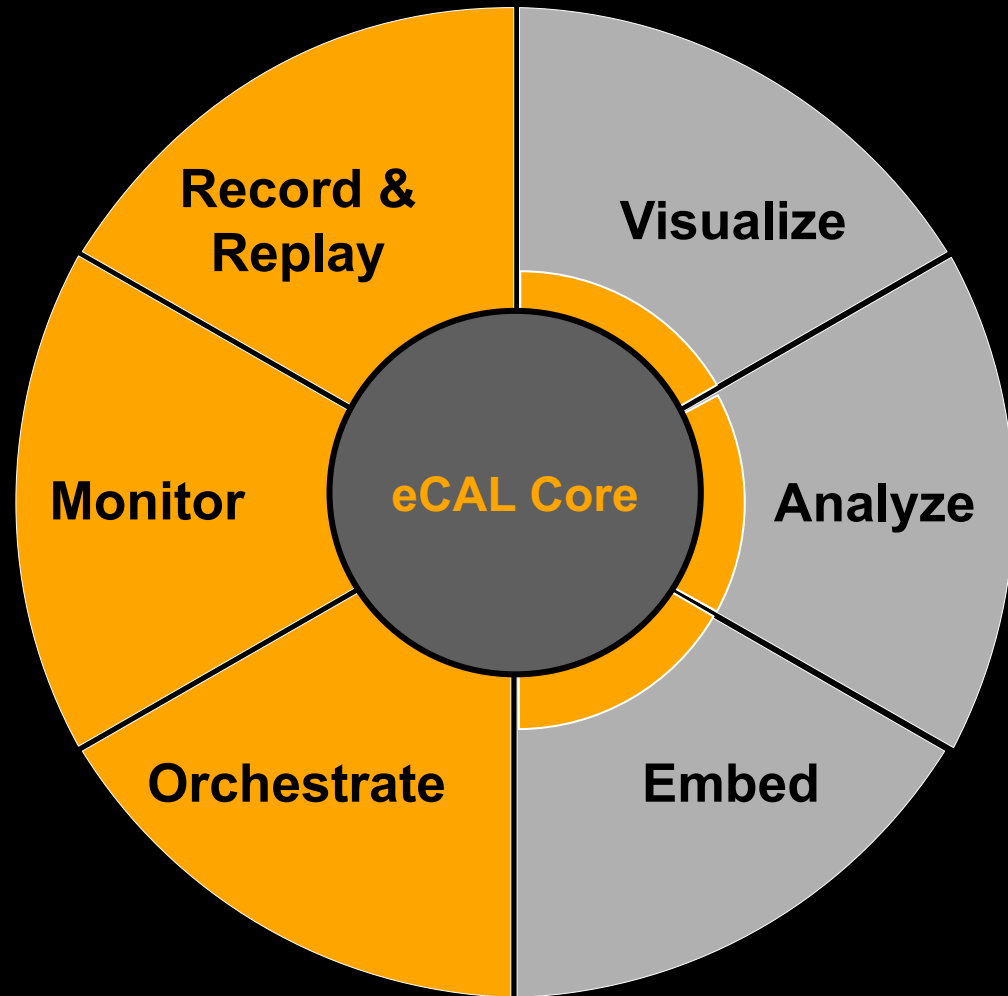
Visualizing Data using Foxglove Studio

<http://ecal.io>

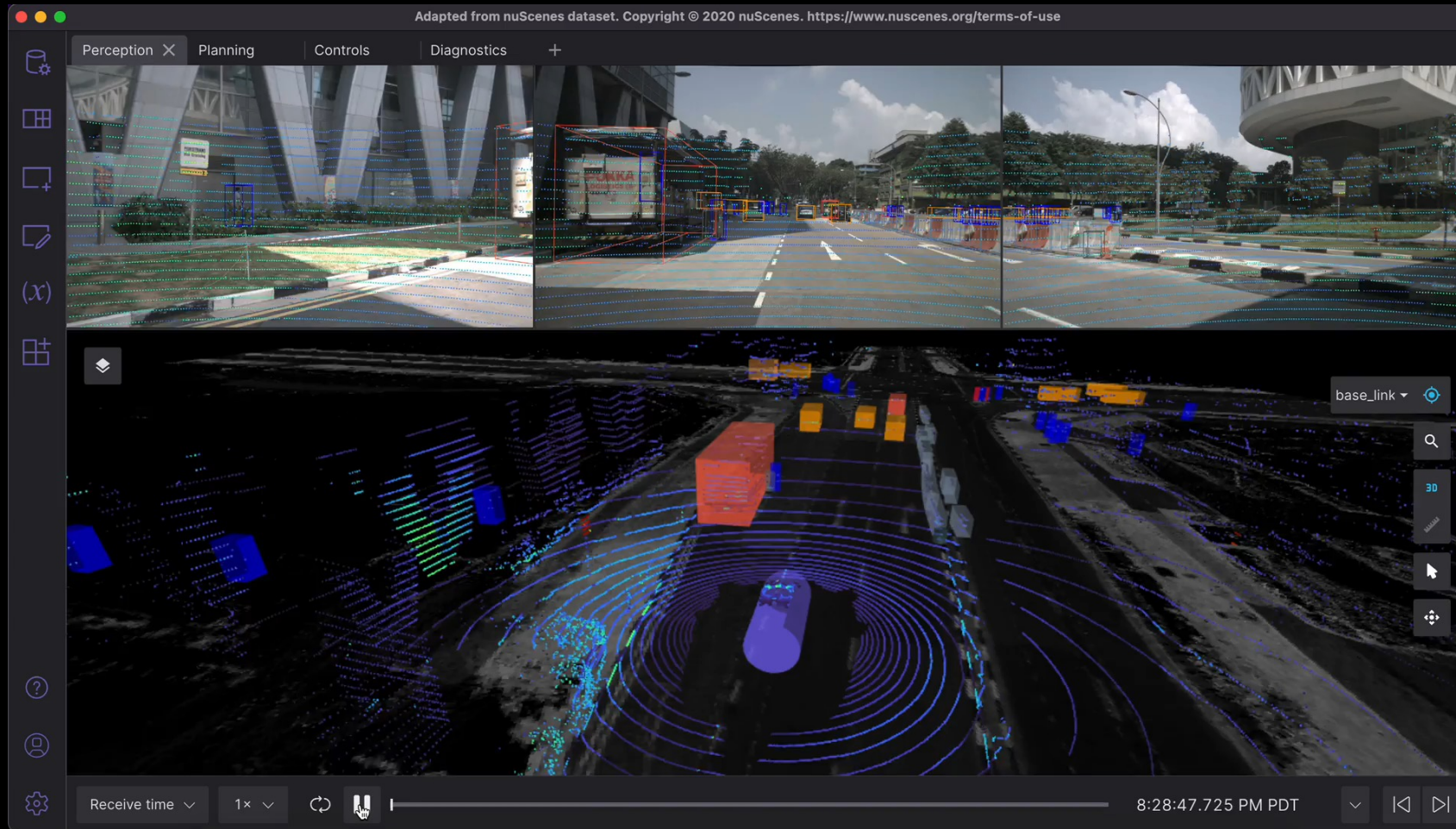
About us



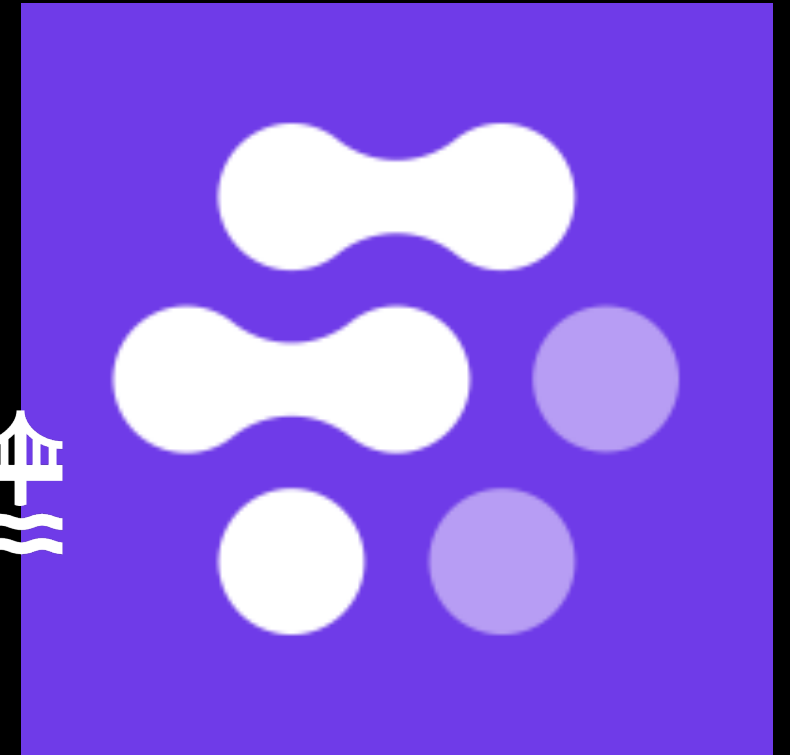
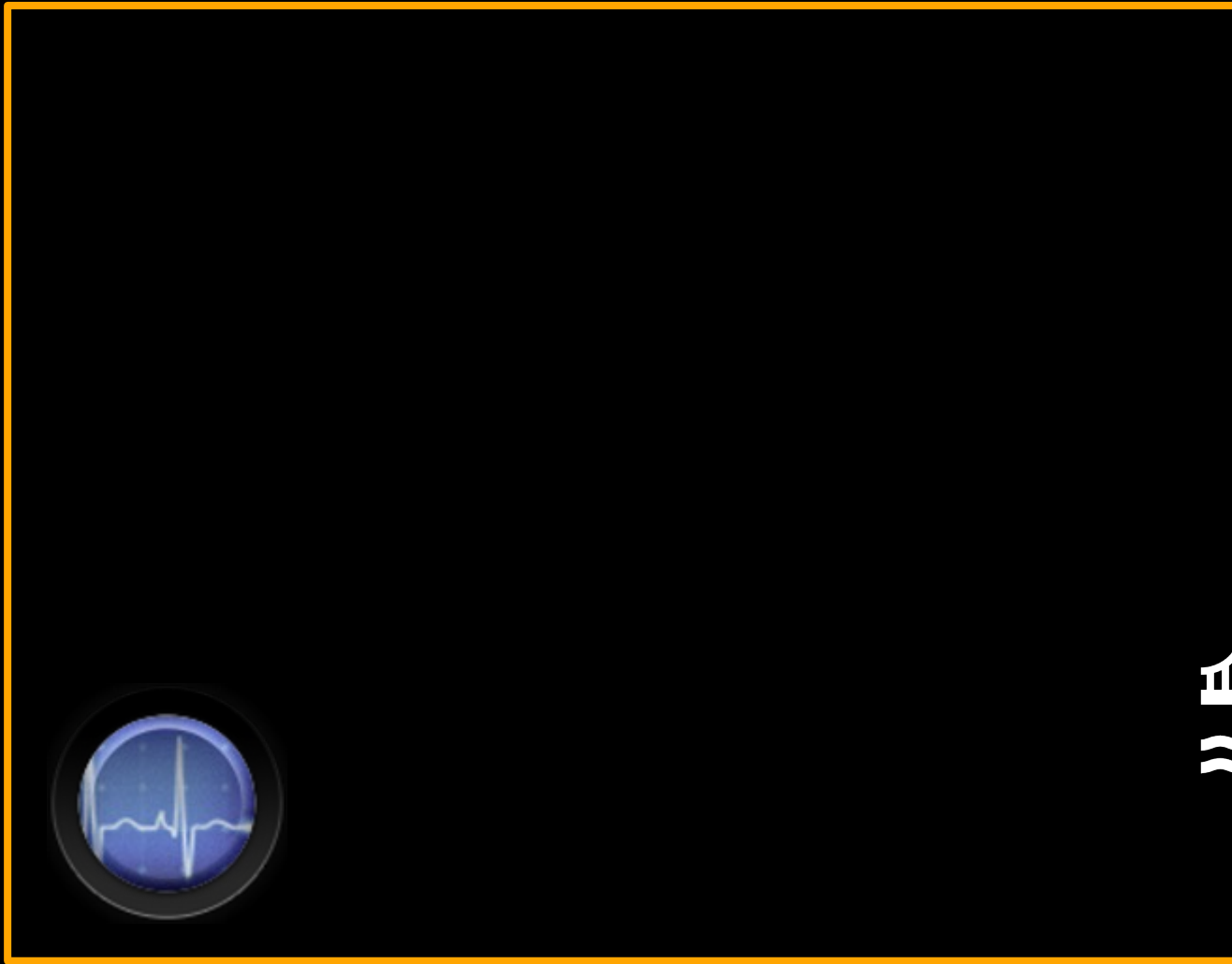
eCAL ecosystem



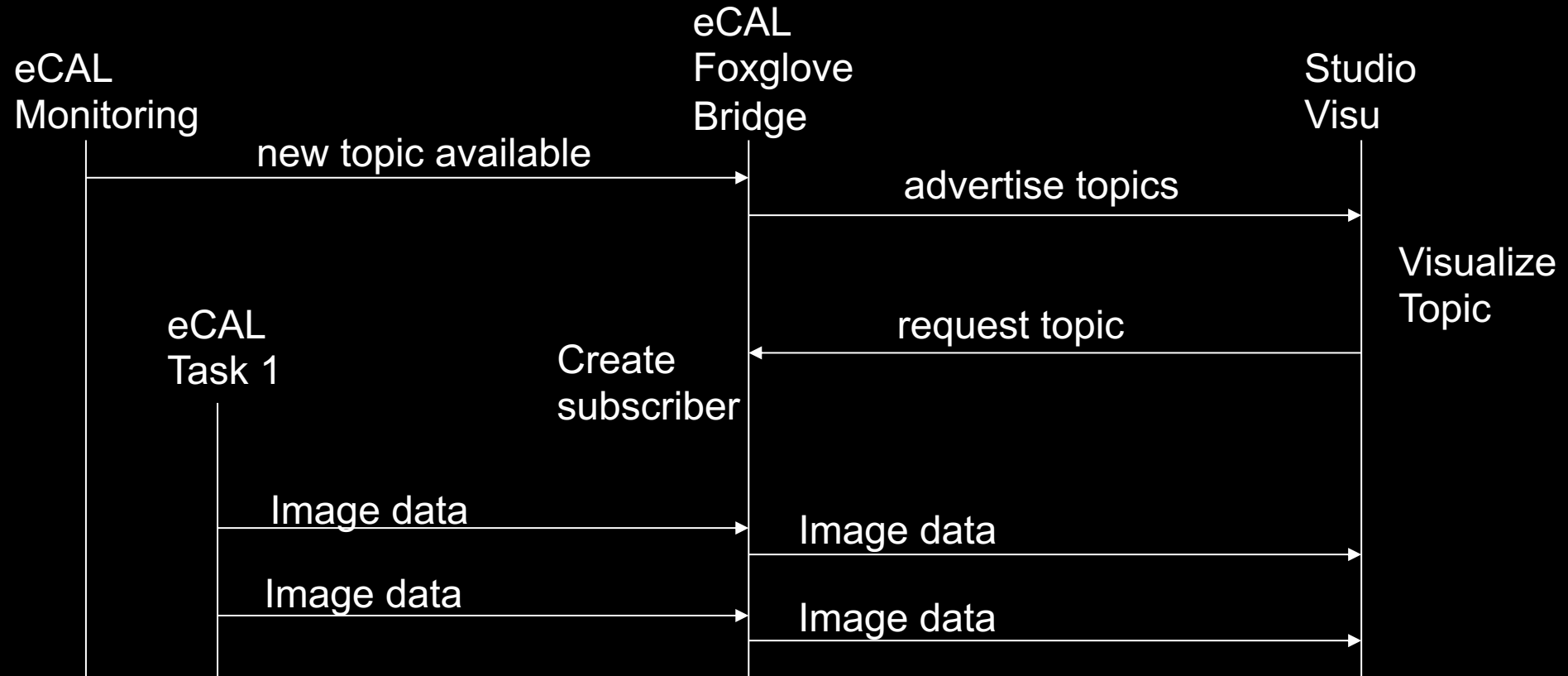
Foxglove Studio



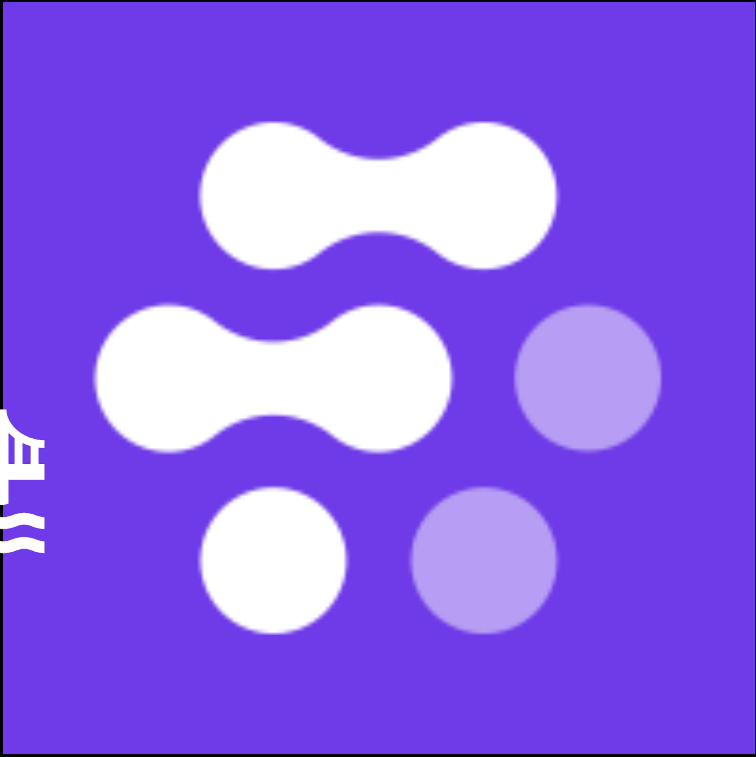
eCAL Foxglove Bridge architecture



eCAL Foxglove Bridge architecture



Demo Setup



Demo

The screenshot displays the Eclipse IDE environment with several windows open:

- Panel Selection:** A sidebar on the left allows selecting and editing various panels. The selected panels include:
 - 3D:** Display markers, camera images, meshes, URDFs, and more in a 3D scene.
 - Data Source Info:** View details like topics and timestamps for the current data source.
 - Diagnostics - Detail (ROS):** Display ROS DiagnosticArray messages for a specific hardware_id.
 - Diagnostics - Summary (ROS):** Display a summary of all ROS DiagnosticArray messages.
 - Gauge:** A circular gauge visualization.
 - Image:** A 2D camera view of a road scene with bounding boxes.
- eCAL Monitor:** A window showing a table of topics and processes. The table is filtered by Process (FRLBKREW) and shows data for eCALPlayGUI and annotate_images topics.
- eCAL Player:** A window for playing back recorded data. It shows a list of channels (camera/cam_*) and playback controls like 'Limit Playback range' and 'Limit Playback speed'.

Host / Process	Topic	Direction	PID	Message Type	Size [Byte]	Drops	Data Clock	Frequency [Hz]
FRLBKREW	eCALPlayGUI							
	__sim_time__	publisher	25664	proto:eCAL.pb.SimTime	0	0	82190	1.96
	__ecalplay_state__	publisher	25664	proto:eCAL.pb.play.State	0	0	82190	1.96
annotate_images	camera/cam_front_left	subscriber	16056	proto:foxglove.RawImage	6958120	0	91	0
	annotations/cam_front_left	publisher	16056	proto:foxglove.ImageAn...	0	0	91	0
annotate_images	camera/cam_rear_center	subscriber	21464	proto:foxglove.RawImage	6958120	0	91	0
	annotations/cam_rear_center	publisher	21464	proto:foxglove.ImageAn...	0	0	91	0

Channel	Total frames	Published messages
camera/cam_front_center	40	0
camera/cam_front_left	40	0
camera/cam_front_right	40	0
camera/cam_rear_center	40	0
camera/cam_side_left	40	0
camera/cam_side_right	40	0

Summary

- eCAL comes with powerful tools
- eCAL has been integrated with existing tools
- Foxglove Studio is the newest integration for the eCAL ecosystem
- Which existing tool should we integrate next?

Attributions

- eCAL: [Welcome to Eclipse eCAL™ — Eclipse eCAL™ \(eclipse-ecal.github.io\)](https://eclipse-ecal.github.io)
- ROS: [ROS: Home](https://www.ros.org/)
- MathWorks: [MathWorks – Entwickler von MATLAB und Simulink - MATLAB & Simulink](https://www.mathworks.com/)
- Foxglove: [Foxglove - Visualizing and debugging your robotics data – Foxglove](https://foxglove.dev/)
- Driving Dataset: [Driving Dataset | a2d2.audi](https://a2d2.audi.com/)
- Object Detection: [Object detection task guide | MediaPipe | Google for Developers](https://ai.google.dev/robotics/object-detection/task-guide)